

(EELS) Data analysis basics

Francisco de la Peña



Diamond Light Source
2nd of March 2020

1 Introduction

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2 Model based quantification

- The integration method
- The curve fitting method
- Multi-dimensional curve fitting
- Practical application: Analytical tomography

3 Machine learning

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- EELS core-loss analysis

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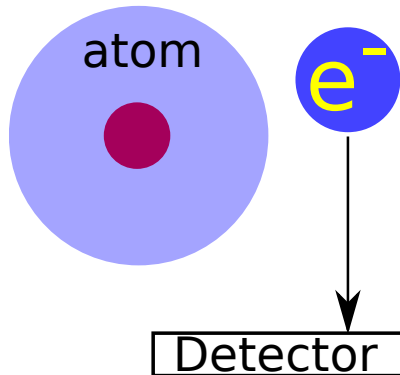
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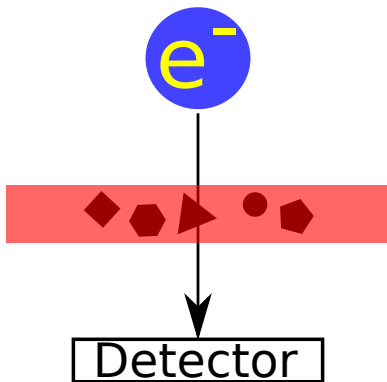
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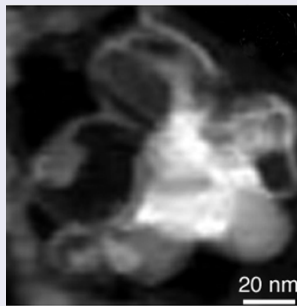
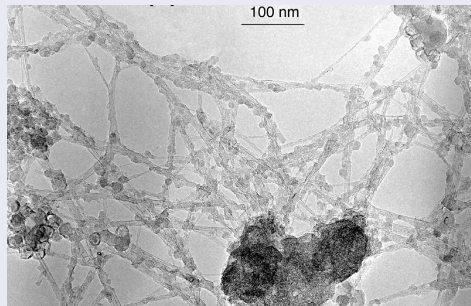
Why do we care about data processing at all?



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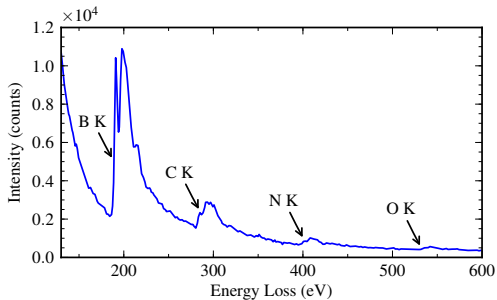


Boron-nitride nano-particles characterisation by EM

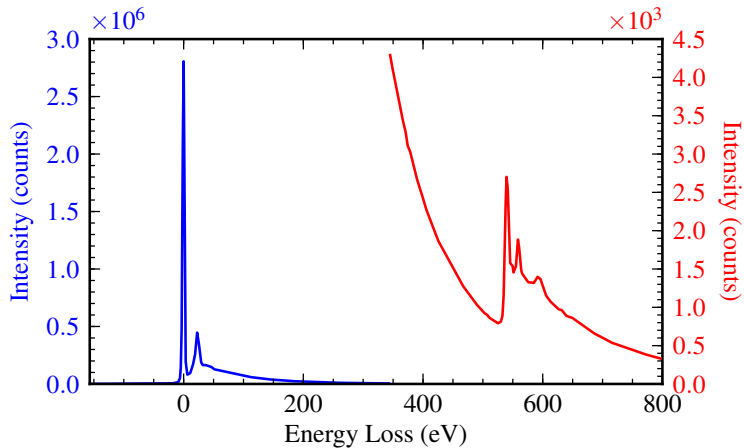


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EELS spectrum from BN NPs

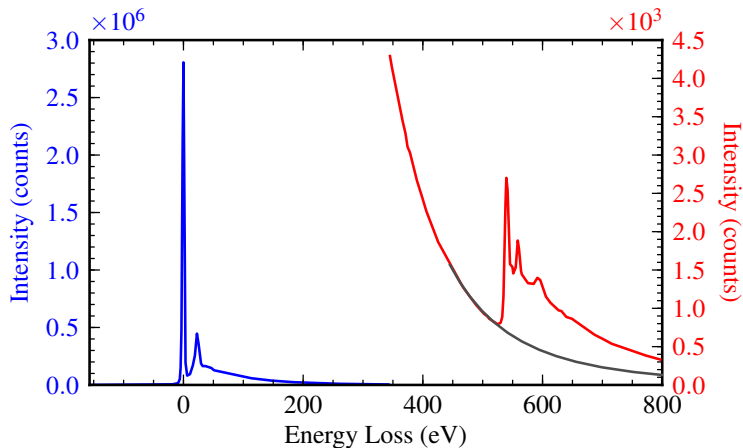


The “windows” method



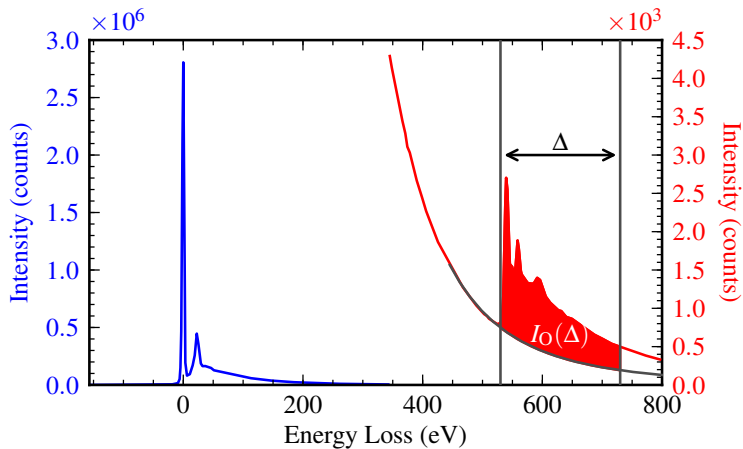
The “windows” method

$$N_0 \approx \text{———}$$



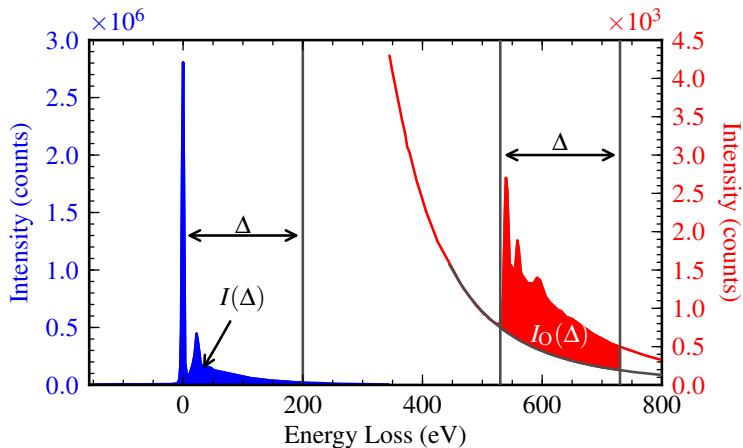
The “windows” method

$$N_O \approx \frac{I_O(\Delta, \beta)}{\beta}$$



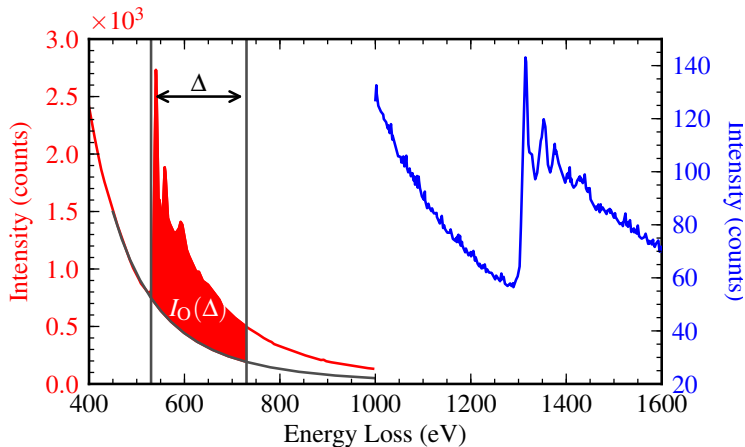
The “windows” method

$$N_0 \approx \frac{I_0(\Delta, \beta)}{I(\Delta, \beta)} \sigma_0^{-1}(\Delta, \beta)$$



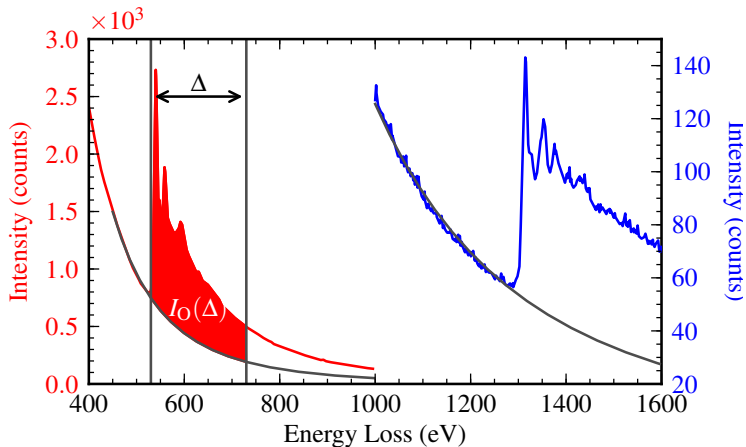
The “windows” method

$$N_O \approx \frac{I_O(\Delta, \beta)}{I(\Delta, \beta)} \sigma_O^{-1}(\Delta, \beta) \quad N_{Mg} \approx \frac{I_{Mg}(\Delta, \beta)}{I(\Delta, \beta)} \sigma_{Mg}^{-1}(\Delta, \beta)$$



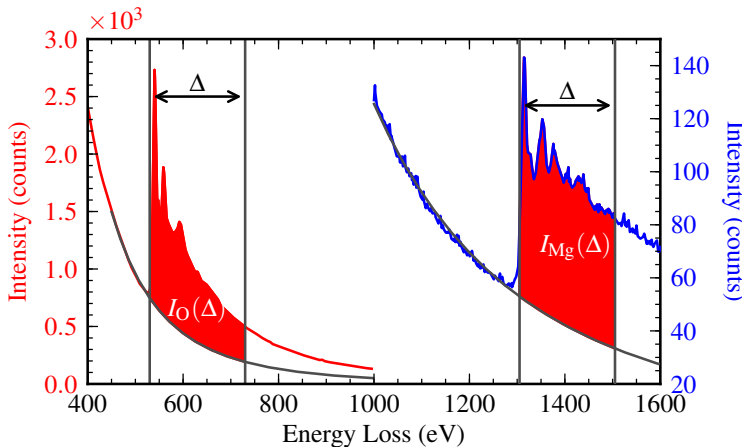
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$$N_{\text{O}} \approx \frac{I_{\text{O}}(\Delta, \beta)}{I(\Delta, \beta)} \sigma_{\text{O}}^{-1}(\Delta, \beta) \quad N_{\text{Mg}} \approx \frac{I_{\text{Mg}}(\Delta, \beta)}{I(\Delta, \beta)} \sigma_{\text{Mg}}^{-1}(\Delta, \beta)$$



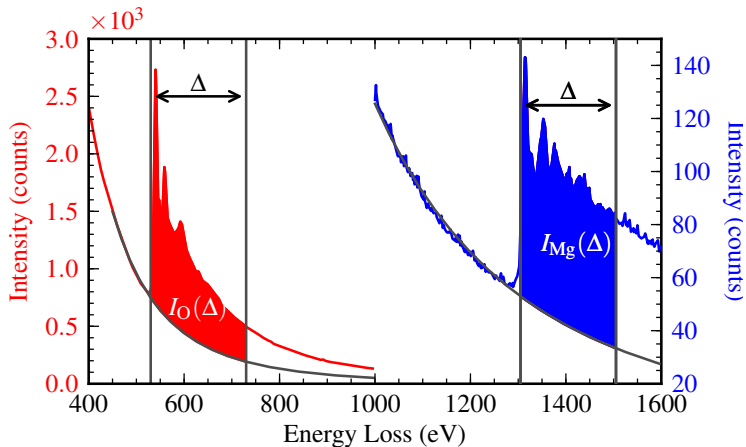
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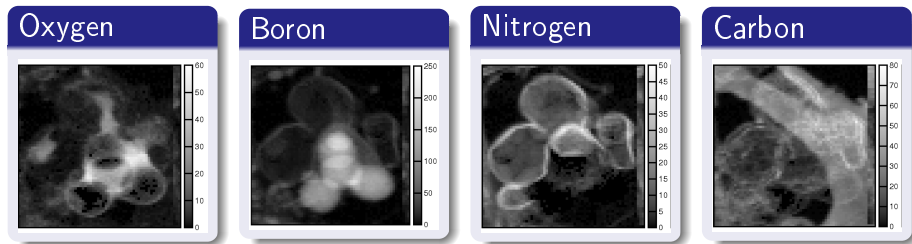


The “windows” method

$$\frac{N_{\text{O}}}{N_{\text{Mg}}} \approx \frac{I_{\text{O}}(\Delta, \beta)}{I_{\text{Mg}}(\Delta, \beta)} \frac{\sigma_{\text{Mg}}(\Delta, \beta)}{\sigma_{\text{O}}(\Delta, \beta)}$$



EELS elemental of BN nanoparticle



Arenal et al., Ultramicroscopy 2008

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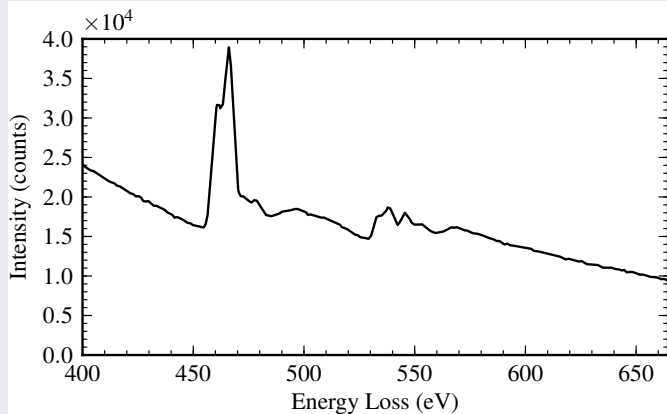
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- Overlapping edges
- It always returns a result (what feels good) but, how do we know that it is correct?
- Only analyses a fraction of the available signal (non-optimal SNR)
- Useful information gets lost (fine structures changes, energy onset shifts...)

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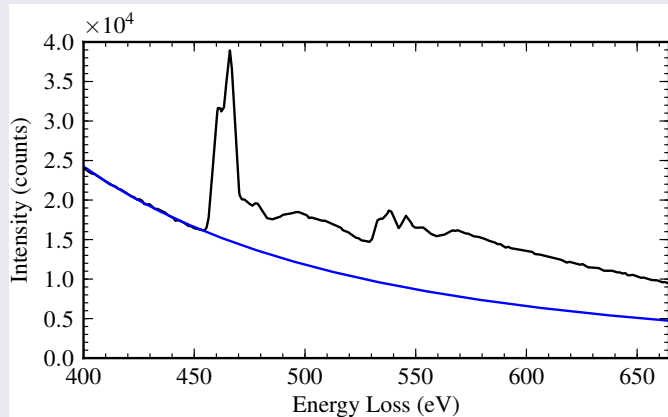
The curve fitting method: an example

SrTiO₃ Spectrum



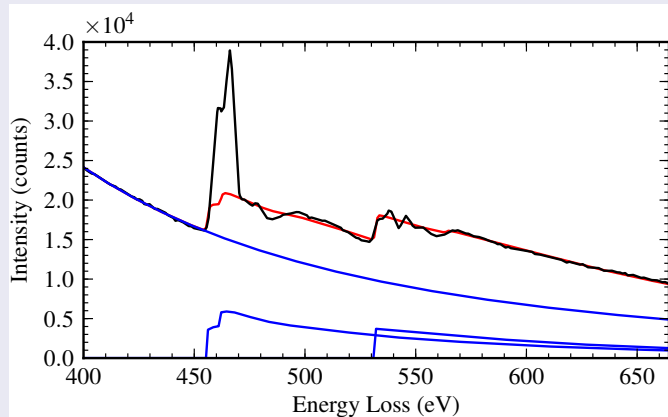
The curve fitting method: an example

$$M(E) = AE^{-r}$$



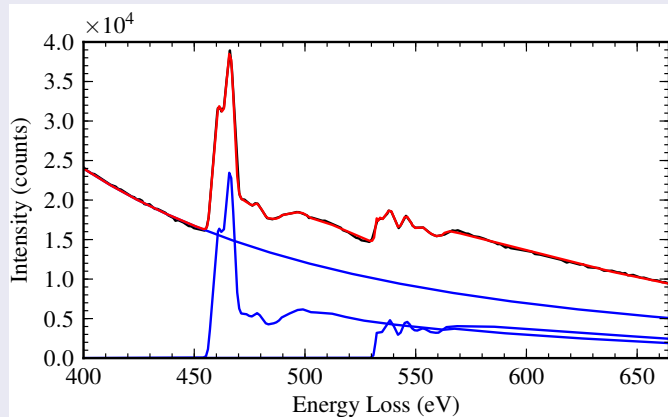
The curve fitting method: an example

$$M(E) = AE^{-r} + I_{\text{Ti}}\sigma_{\text{Ti}}(E) + I_{\text{O}}\sigma_{\text{O}}(E) * L(E)$$



The curve fitting method: an example

$$M(E) = AE^{-r} + (N_{\text{Ti}} f_{\text{Ti}}(E) \sigma_{\text{Ti}}(E) + N_{\text{O}} f_{\text{O}}(E) \sigma_{\text{O}}(E)) * L(E)$$



- There is a *known* function, f , that relates the *independent variable* X and the *dependent variable* Y . $Y \approx f(X, \beta) + \varepsilon(f(X, \beta))$

Assumptions

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- There is a *known* function, f , that relates the *independent variable* X and the *dependent variable* Y . $Y \approx f(X, \beta) + \varepsilon(f(X, \beta))$
- The number of unknown parameters, β is *equal or less* than the number of different observations of the independent variable
- The probability distribution of the statistical error (ε) is known

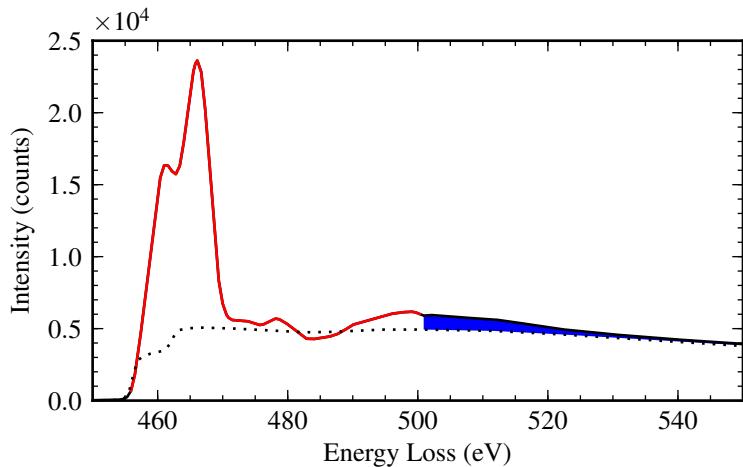
Components of the model

Parametric model of the high energy loss spectrum for elemental and bonding quantification:

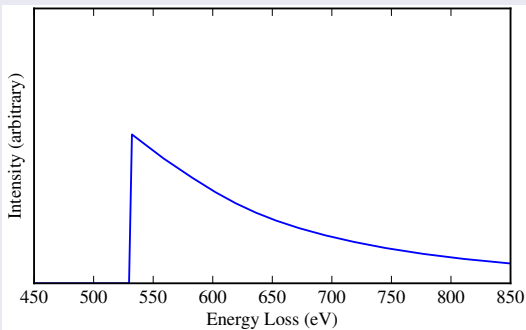
$$M(E; \text{parameters}) = AE^{-r} + \left(\sum_i N_i f_i(E) \int_0^{q(\beta)} \sigma_i(E, q) dq \right) * L(E)$$

- AE^{-r} : background model
- σ_i^{FS} : cross section of each ionization edge, i
- N_i : atoms/nm²
- $f_i(E)$: function that mimics the fine structure of each ionization edge, e.g. gaussian, fingerprints, splines...
- $L(E)$: experimental low loss spectrum.

Why adding the fine structure to the model?

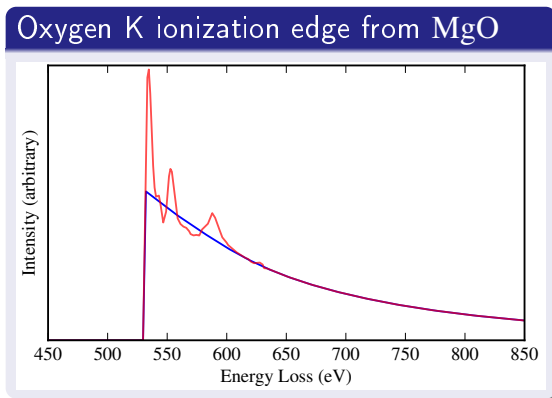


Oxygen K ionization edge from MgO



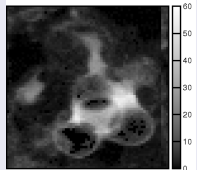
Ionization edge fine structure

- In solids, the first ~ 40 eV are strongly modified by the final density of states \Rightarrow carries bonding information

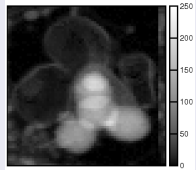


EELS elemental and bonding maps of BN nanoparticle

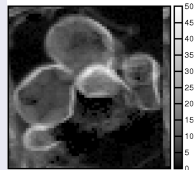
Oxygen



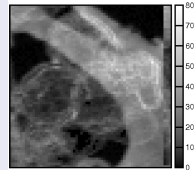
Boron



Nitrogen



Carbon

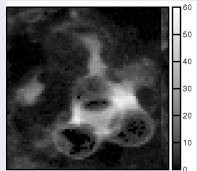


Arenal et al., Ultramicroscopy 2008

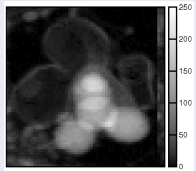


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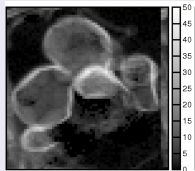
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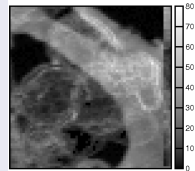
Boron



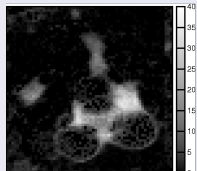
Nitrogen



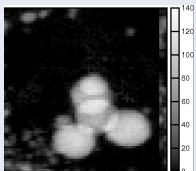
Carbon



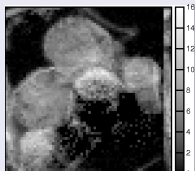
Boron oxide



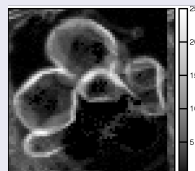
Boron pure



BN \perp



BN \parallel



Arenal et al., Ultramicroscopy 2008



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 - Maximum likelihood estimation (ML)

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- In EELS the noise is a mixture of *Poisson and Gaussian noise*.
- WNNLS can approximate well Poissonian noise when the number of counts is high enough (almost always in EELS)
- Non-linear parameter estimation is an iterative process that *is very sensitive to the starting parameters*

- Steele, J., Titchmarsh, J., Chapman, J., and Paterson, J. (1985). A single-stage process for quantifying electron energy-loss spectra. *Ultramicroscopy*, 17(3):273–276.

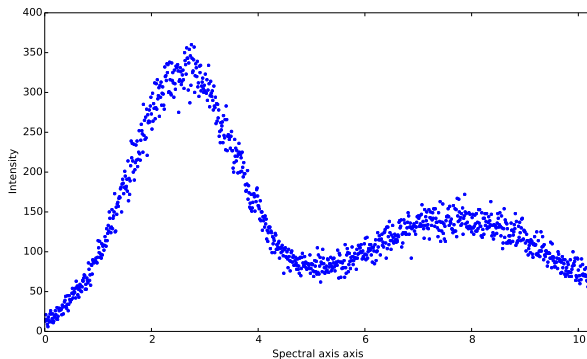
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- EELSModel <http://www.eelsmodel.ua.ac.be/> (open source)
- HyperSpy <http://hyperspy.org> (open source)
- Digital Micrograph

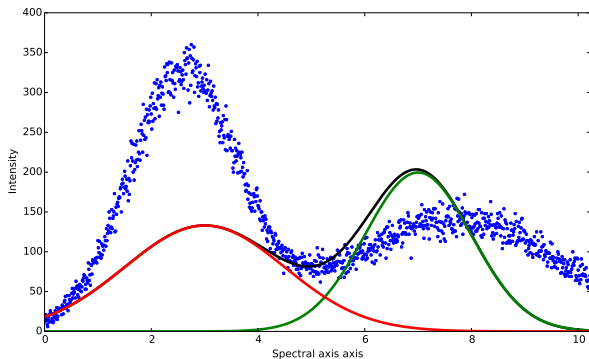
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Non-linear optimisation routine



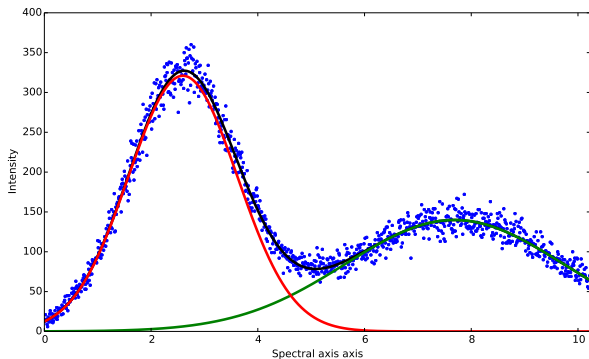
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Non-linear optimisation routine



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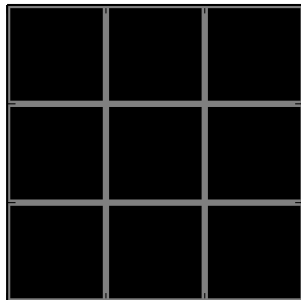
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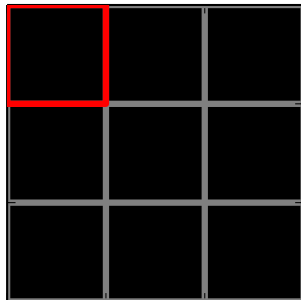
Fitting routine n-dimensions

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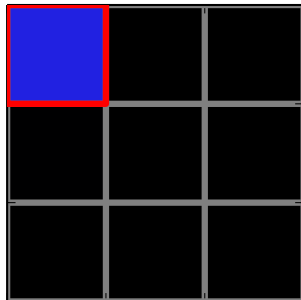
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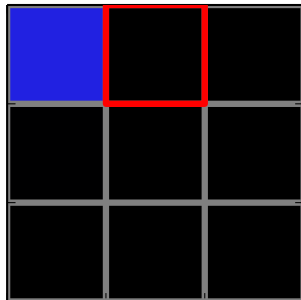
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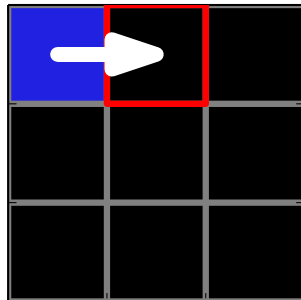
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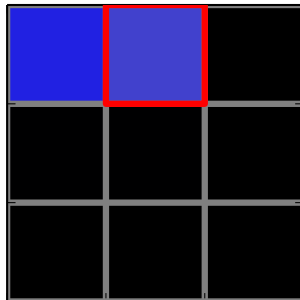
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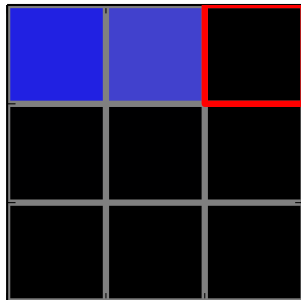
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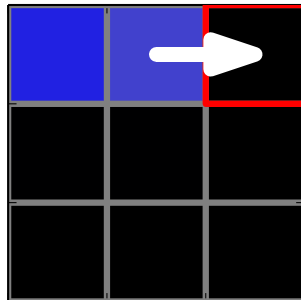
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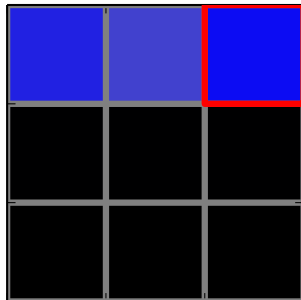
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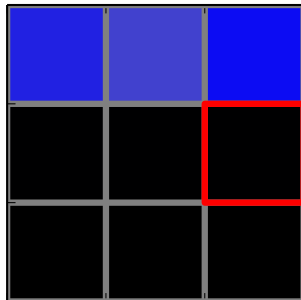
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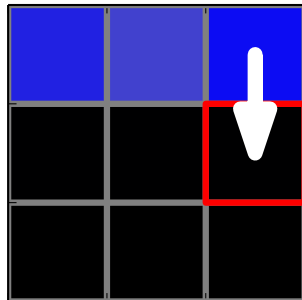
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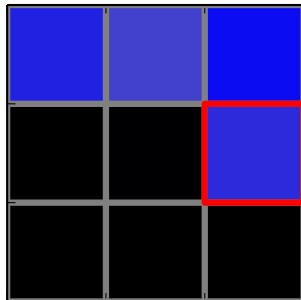
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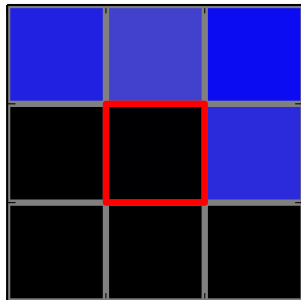
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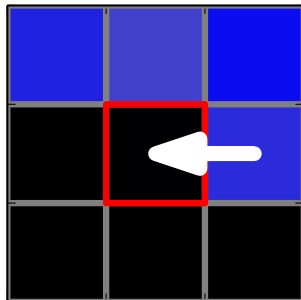
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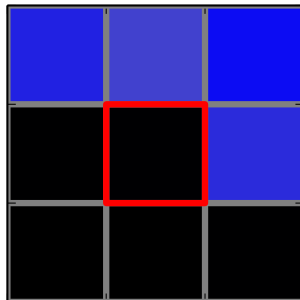
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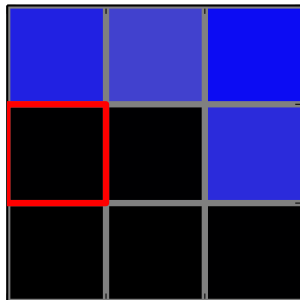
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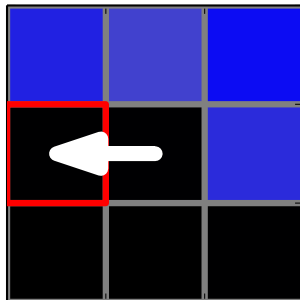
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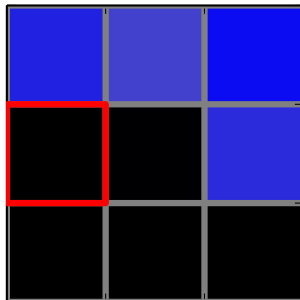
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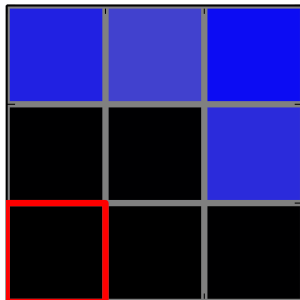
Fitting routine n-dimensions

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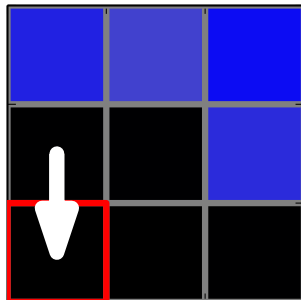
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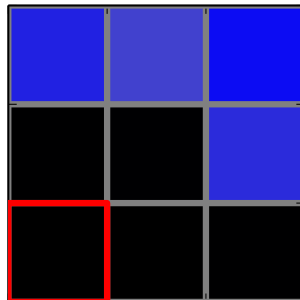
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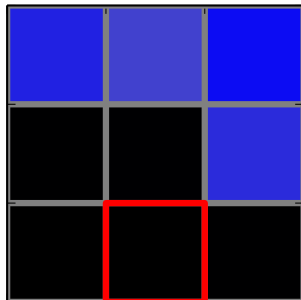
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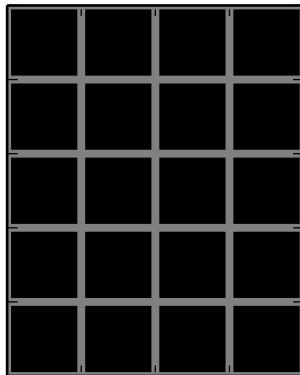


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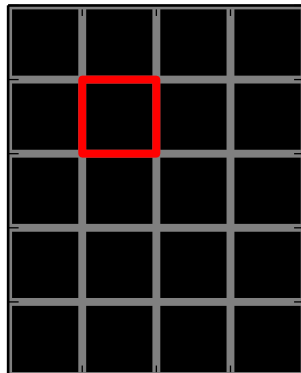


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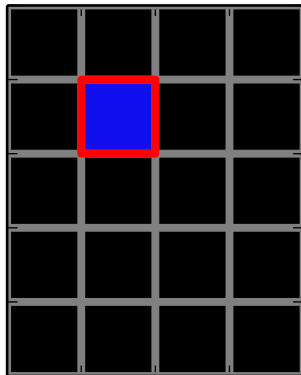
T. Ostasevicious *et al*, EMC2016 proceedings

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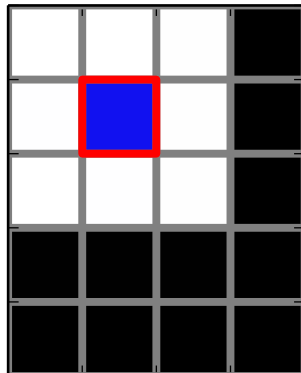
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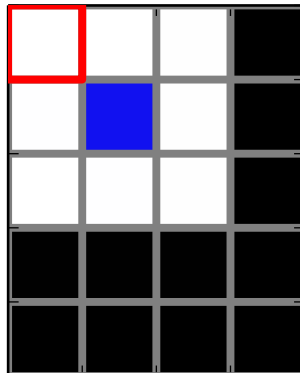
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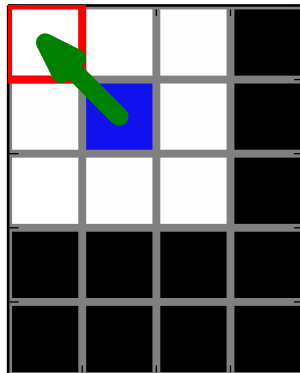
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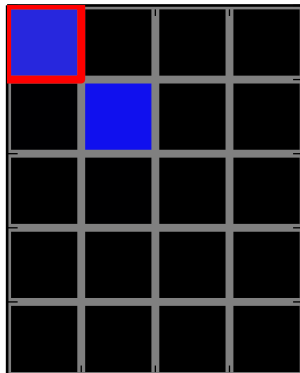
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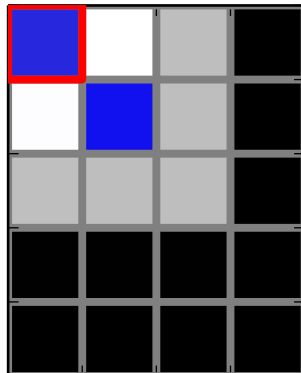
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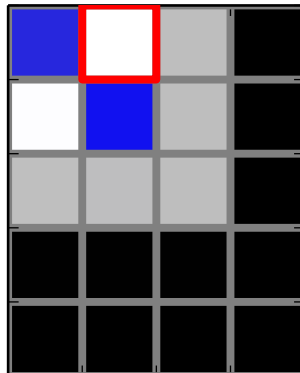
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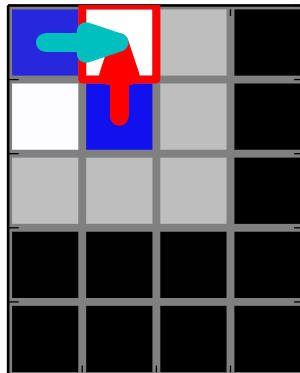
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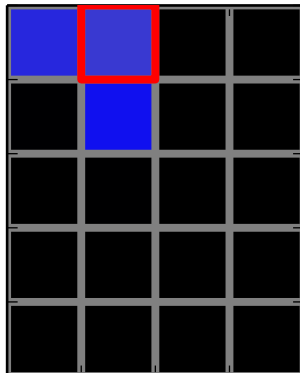
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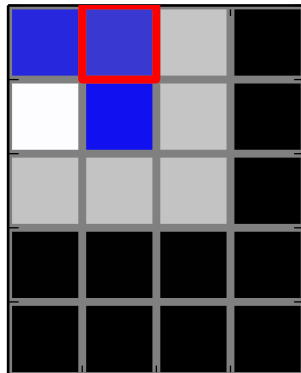
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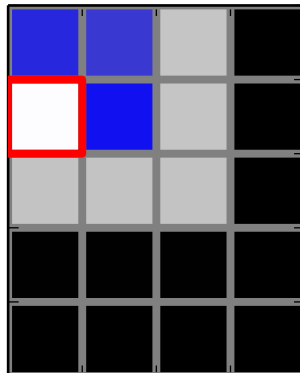
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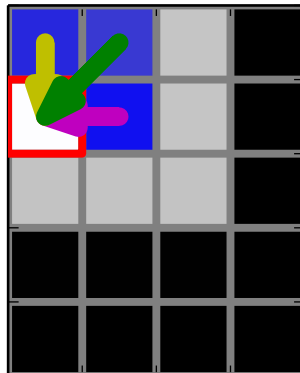
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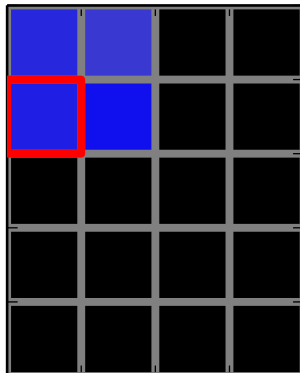
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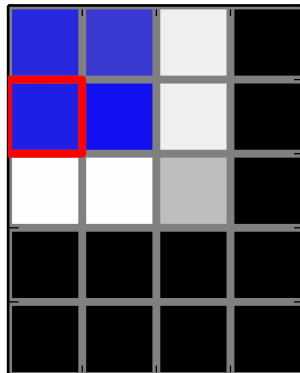
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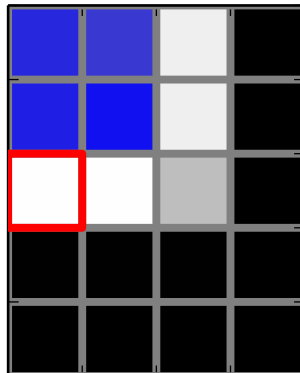
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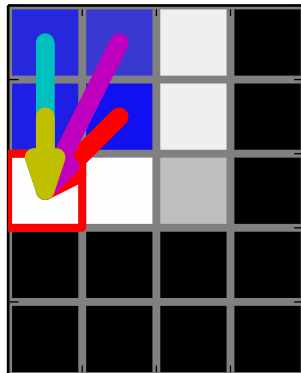
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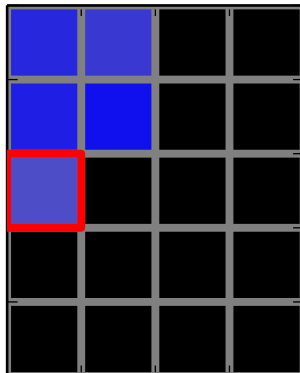
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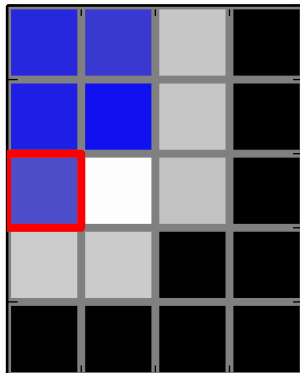
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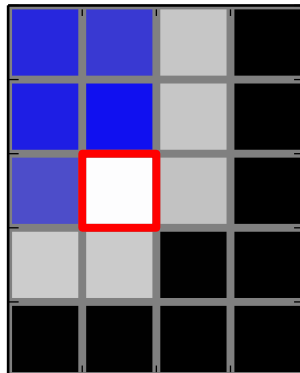
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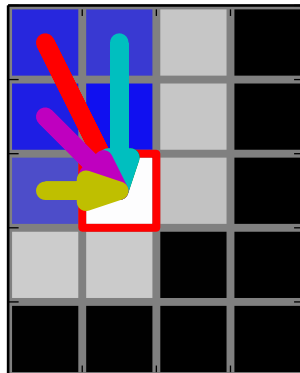
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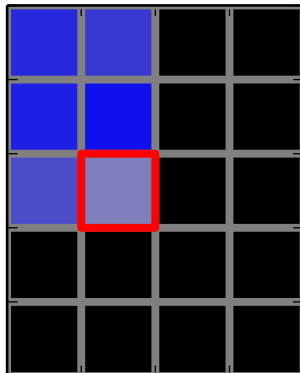
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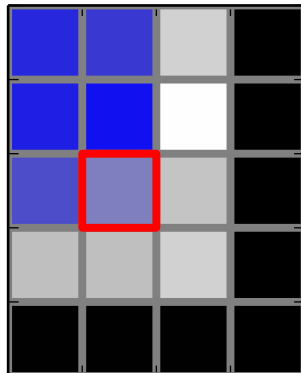
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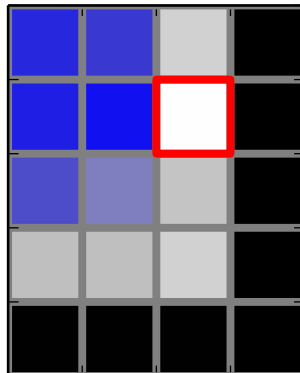
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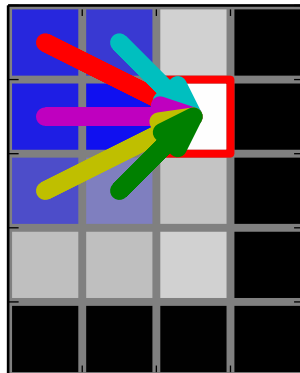
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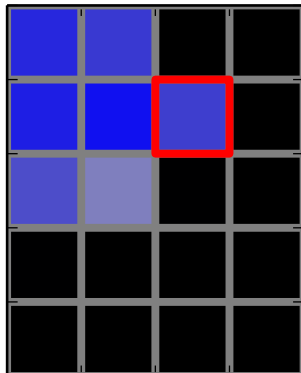
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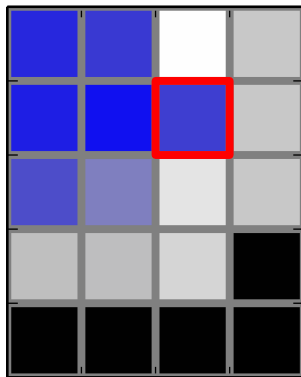
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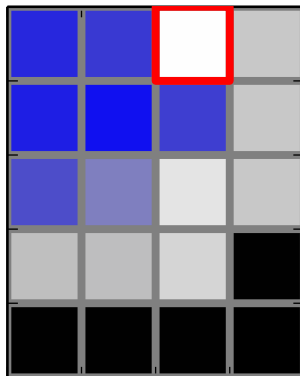
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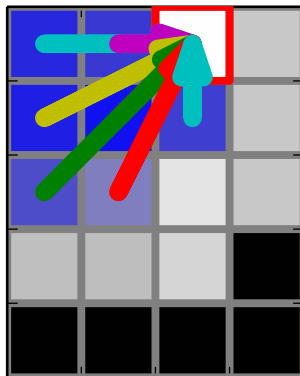
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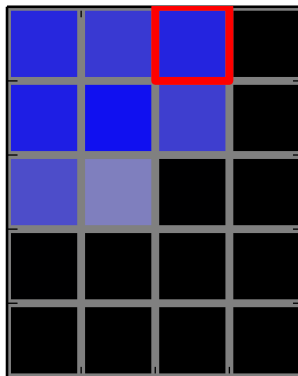
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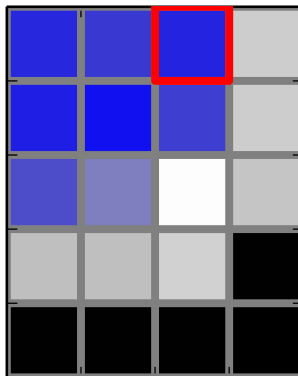
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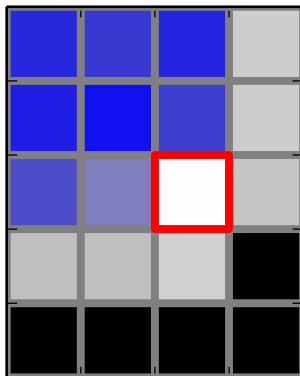
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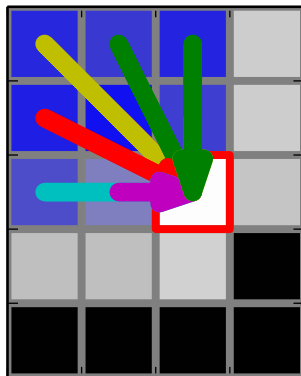
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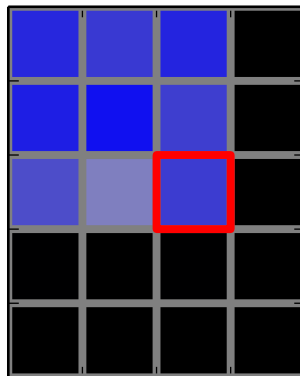
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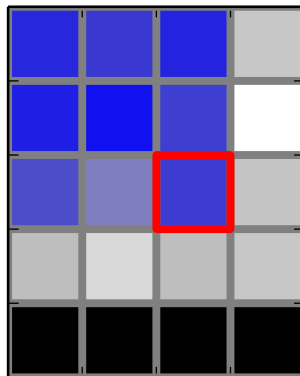
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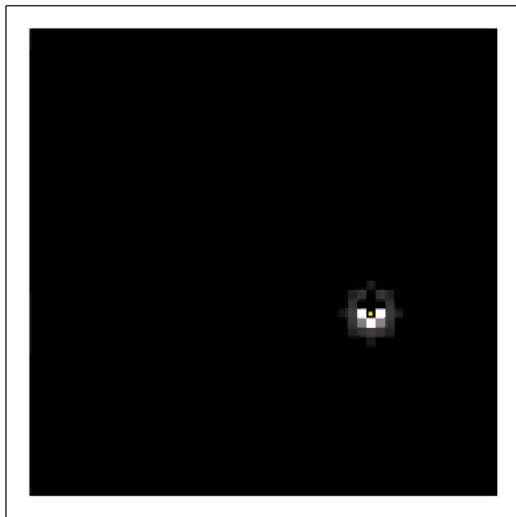
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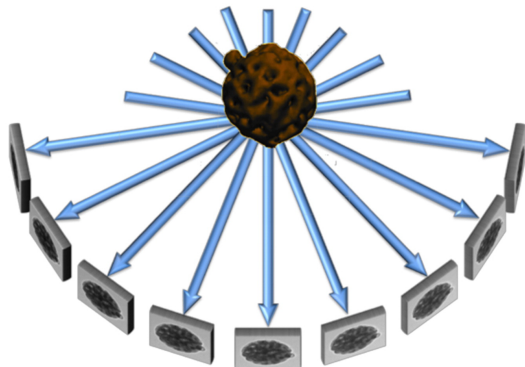
SAMFire parallel fitting example



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Transmission electron tomography



Radon transform

$$Y_{\theta} = R_{\theta}(X) \quad i = -70 \dots 70$$

Figure from O. Ersen et al., *Materials Today* 18, 2015

Tomography as a constrained optimisation problem

$$Y_\theta = R_\theta(X) + \text{noise} \quad \theta = -70, \dots, +70$$

Tomography as a constrained optimisation problem

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$$X^* = \arg \min_X \left\{ \|R_\theta(X) - Y_\theta\|_2^2 + \lambda f(X) \right\}$$

Tomography as a constrained optimisation problem

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Useful regularisation functions are:

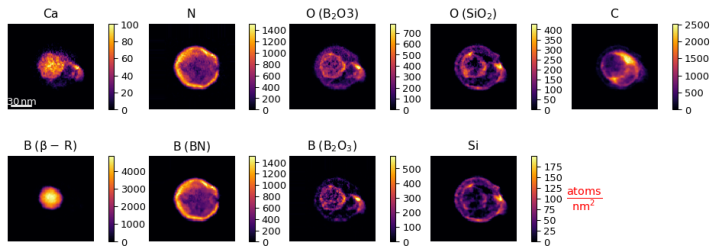
- L_1 – norm: promotes sparsity
- Total variation: promotes sparsity in the gradient

For EM applications see:

- Leary, Rowan, et al. , *Ultramicroscopy* 131 (2013)
- Goris, Bart, et al. , *Ultramicroscopy* 113 (2012)

SAMFire application - Quantitative bonding tomography

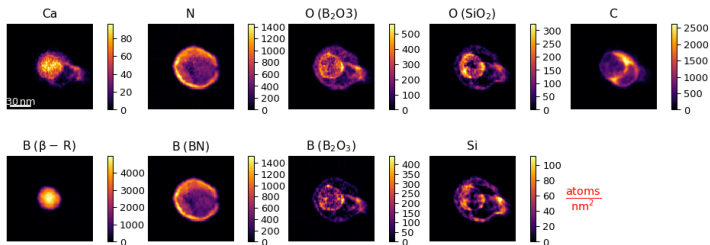
Tilt angle 0.0°



de la Peña, EMC 2016 proceedings

SAMFire application - Quantitative bonding tomography

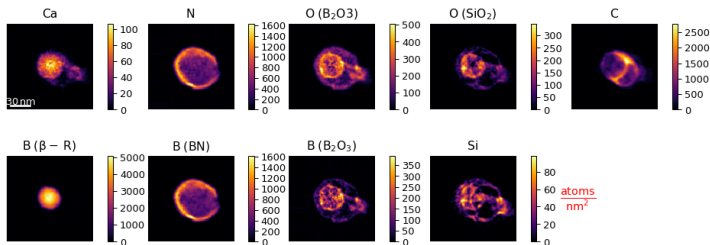
Tilt angle 17.5°



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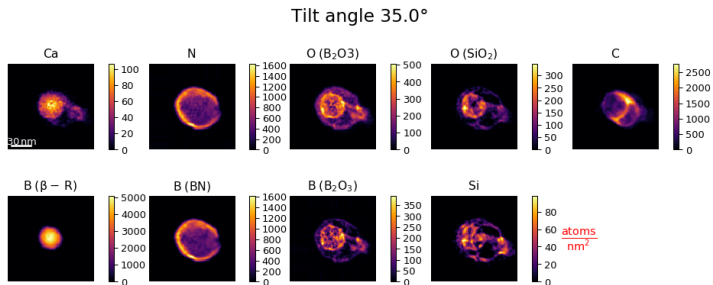
SAMFire application - Quantitative bonding tomography

Tilt angle 35.0°



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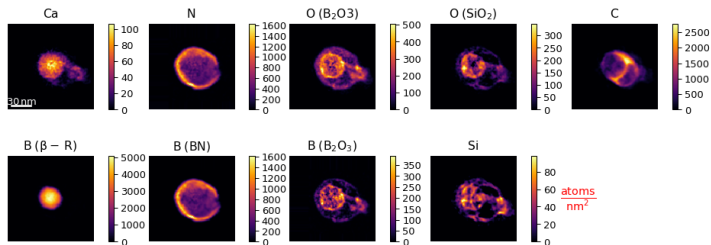
SAMFire application - Quantitative bonding tomography



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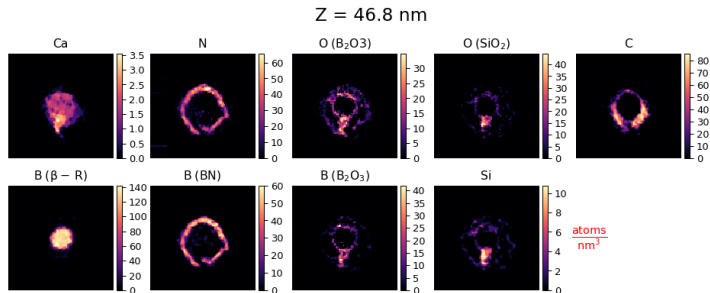
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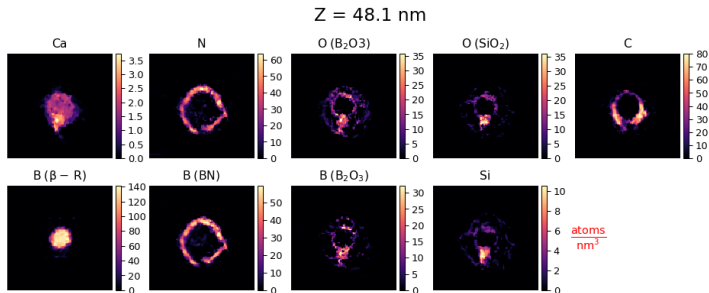
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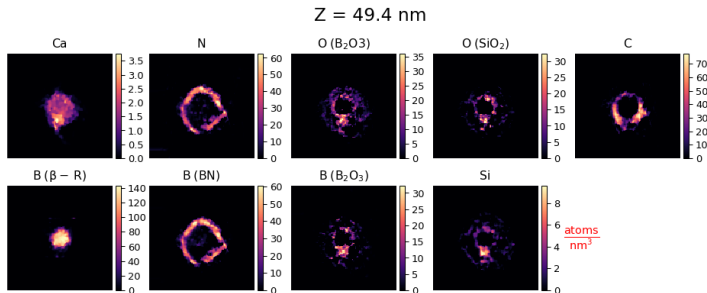
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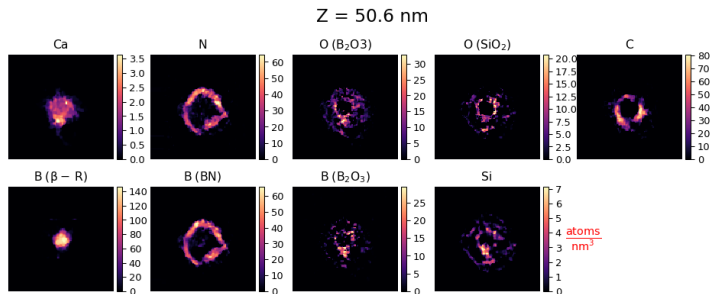
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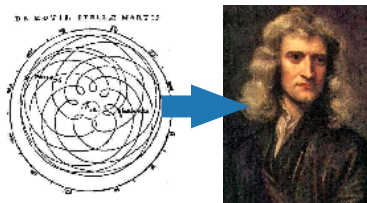
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(Human / Machine) learning



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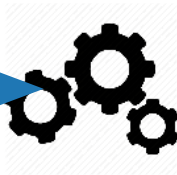
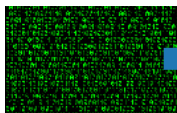


$$F = G \frac{m_1 m_2}{r^2}$$

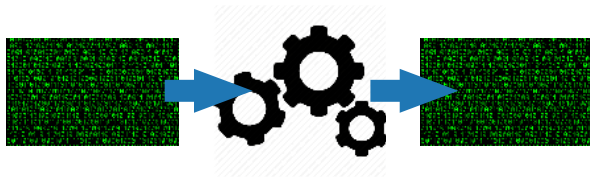
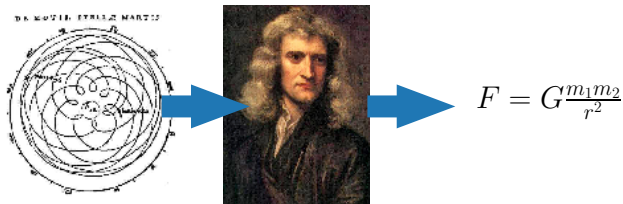
(Human / Machine) learning



$$F = G \frac{m_1 m_2}{r^2}$$



(Human / Machine) learning



(Human / Machine) learning electron microscopy



Human learning :

$$i\hbar \frac{\partial}{\partial t} \Psi(\mathbf{r}, t) = \left[\frac{-\hbar^2}{2\mu} \nabla^2 + V(\mathbf{r}, t) \right] \Psi(\mathbf{r}, t)$$

(Human / Machine) learning electron microscopy



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4 Summary

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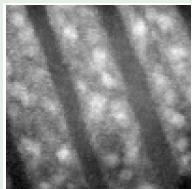
Spinodally decomposed $\text{SnO}_2/\text{TiO}_2$ multilayers

HAADF

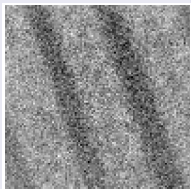


Spinodally decomposed $\text{SnO}_2/\text{TiO}_2$ multilayers

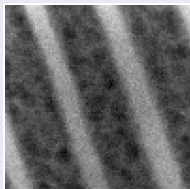
HAADF



Tin



Titanium

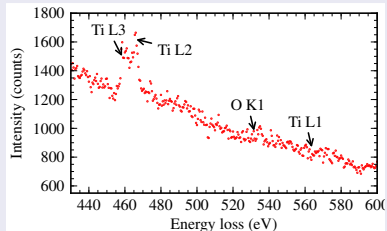


Oxygen

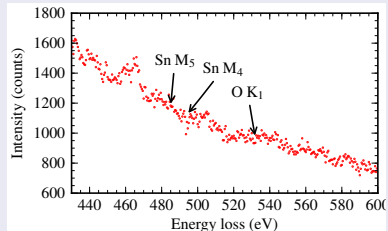


The problem: overlapping peaks and noise

EEL spectrum Ti rich



EEL spectrum Sn rich



Linear mixing

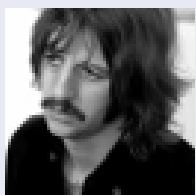
Linearity assumption

$$[a_{i,j}]_{10000 \times (64 \times 64)} = [u_{i,j}]_{(10000) \times 4} \times [v_{i,j}]_{4 \times (64 \times 64)}$$

Paul



Ringo



George



John



Linear mixing

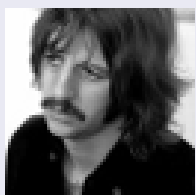
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Paul



Ringo



George



John



Mix 1



Mix 2



Mix 3



Mix 4



$$[a_{i,j}]_{I \times I} \times S = \tilde{S}$$

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \\ a_{41} & a_{42} & a_{43} & a_{44} \end{pmatrix} \times \begin{pmatrix} \text{Image 1} \\ \text{Image 2} \\ \text{Image 3} \\ \text{Image 4} \end{pmatrix} = \begin{pmatrix} \text{Image 1} \\ \text{Image 2} \\ \text{Image 3} \\ \text{Image 4} \end{pmatrix}$$

The diagram illustrates the blind source separation process. On the left, a 4x4 matrix of coefficients a_{ij} is shown. This matrix is multiplied by a column vector of four source images (represented by small icons of people). The result is a column vector of four mixed images, which are visually identical to the source images, representing the output \tilde{S} .

Blind source separation

$$[a_{i,j}]_{I \times I} \times S = \tilde{S}$$

The diagram illustrates the blind source separation process. It shows a matrix of coefficients $[a_{i,j}]_{I \times I}$ multiplied by a source matrix S to produce a mixture matrix \tilde{S} . The matrix $[a_{i,j}]_{I \times I}$ is shown with a large red question mark over it, indicating it is unknown. The source matrix S is shown as a vertical stack of four grayscale images of a person. The mixture matrix \tilde{S} is shown as a vertical stack of four grayscale images of a person, which are mixtures of the sources.

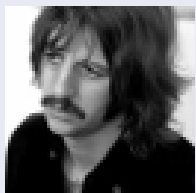
Noisy linear mixing

$$[a_{i,j}]_{10000 \times (64 \times 64)} = [u_{i,j}]_{(10000) \times 4} \times [v_{i,j}]_{4 \times (64 \times 64)}$$

Paul



Ringo



George



John



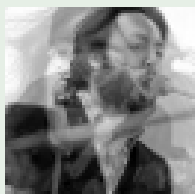
Mix 1



Mix 2



Mix 3



Mix 4



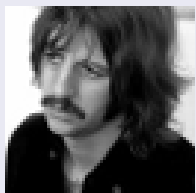
Noisy linear mixing

$$[a_{i,j}]_{10000 \times (64 \times 64)} = [u_{i,j}]_{(10000) \times 4} \times [v_{i,j}]_{4 \times (64 \times 64)} + \text{noise}$$

Paul



Ringo



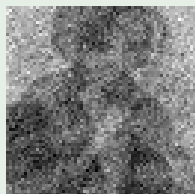
George



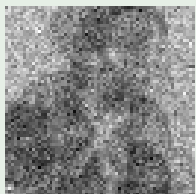
John



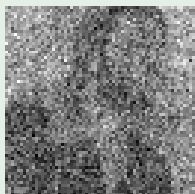
Mix 1



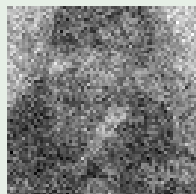
Mix 2



Mix 3



Mix 4



Theorem

Any matrix $A \in \mathbb{R}^{m \times n}$ can be factorised into a singular value decomposition (SVD),

$$A = USV^T \quad (1)$$

where $U \in \mathbb{R}^{m \times m}$ and $V \in \mathbb{R}^{n \times n}$ are orthogonal matrices, and $S \in \mathbb{R}^{m \times n}$ is diagonal with $r = \text{rank}(A)$ leading positive entries. The p diagonal entries of S are denoted σ_i for $i = 1, \dots, p$ where $p = \min\{m, n\}$ and are called the singular values of A . They satisfy the property $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_p$.

Eckart–Young–Mirsky theorem

Dimensionality reduction / low rank approximation

Theorem

Let the SVD of A be given by (1). If $k < r = \text{rank}(A)$ and $A_k = \sum_{i=1}^k \sigma_i u_i v_i^T$, then

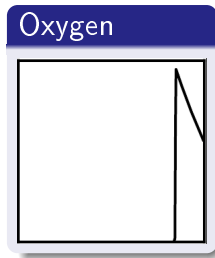
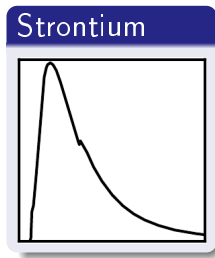
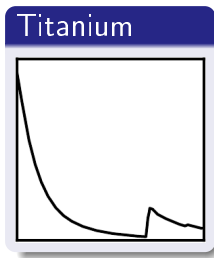
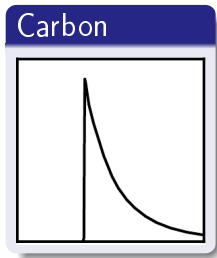
$$\min_{\text{rank}(B)=k} \|A - B\|_2 = \|A - A_k\|_2 = \sqrt{\sum_{i=k+1}^p \sigma_i^2}$$

input image: 1



EELS BSS with The Beatles

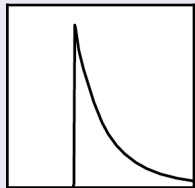
$$[d_{i,j}] \quad \times 1024 = \quad \times 4 \times [s_{i,j}] 4 \times 1024$$



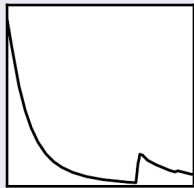
EELS BSS with The Beatles

$$[d_{i,j}]_{(134 \times 134) \times 1024} = [p_{i,j}]_{(134 \times 134) \times 4} \times [s_{i,j}]_{4 \times 1024}$$

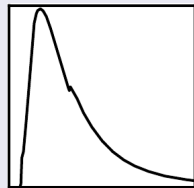
Carbon



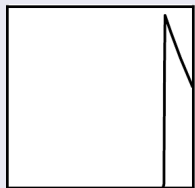
Titanium



Strontium



Oxygen



Carbon



Titanium



Strontium



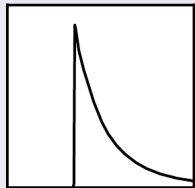
Oxygen



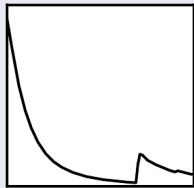
EELS BSS with The Beatles

$$[d_{i,j}]_{(134 \times 134) \times 1024} = [p_{i,j}]_{(134 \times 134) \times 4} \times [s_{i,j}]_{4 \times 1024} + \text{Poisson noise}$$

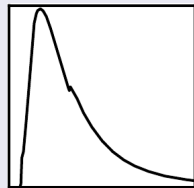
Carbon



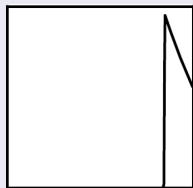
Titanium



Strontium



Oxygen



Carbon



Titanium



Strontium



Oxygen



- Using the synthetic SIs we will test the performance of ICA at estimating the mixing matrix when using the first and second derivative as pre-treatment

Low SNR SI

- 4 elements: C, Sr, Ti, O
- 134×134 pixels
- 1024 energy channels
- Poisson noise
- Average number of counts: $\sim 10^3$

Synthetic SIs for ICA test

- Using the synthetic SIs we will test the performance of ICA at estimating the mixing matrix when using the first and second derivative as pre-treatment

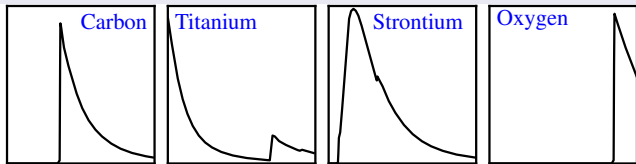
Low SNR SI

- 4 elements: C, Sr, Ti, O
- 134×134 pixels
- 1024 energy channels
- Poisson noise
- Average number of counts: $\sim 10^3$

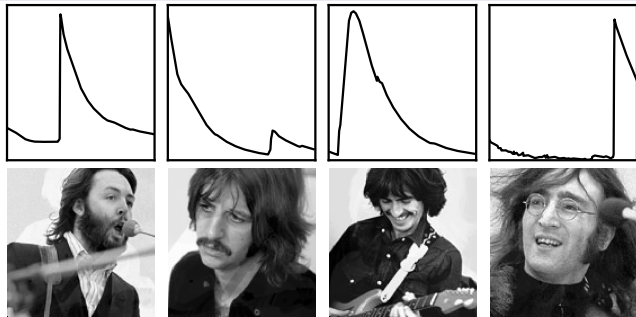
High SNR SI

- 4 elements: C, Sr, Ti, O
- 134×134 pixels
- 1024 energy channels
- Poisson noise
- Average number of counts: $\sim 10^6$

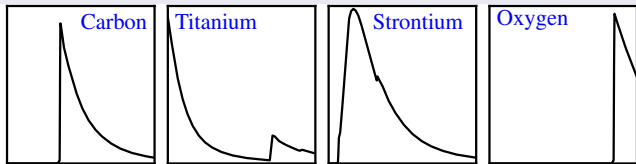
Original spectral components



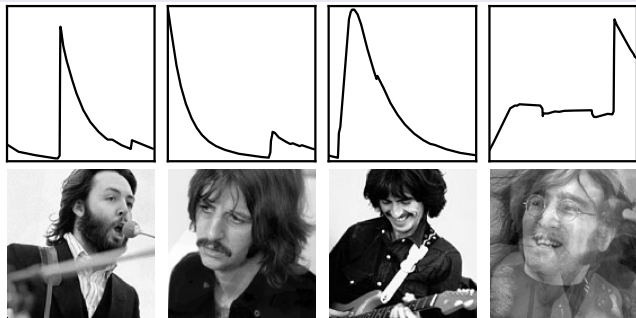
ICA result: Low SNR, first derivative



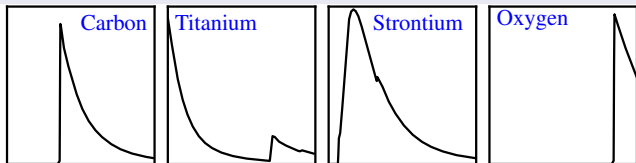
Original spectral components



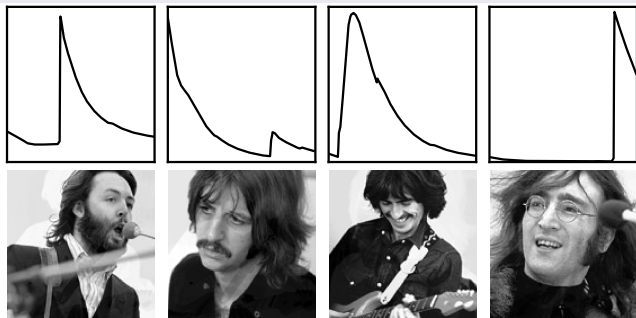
ICA result: Low SNR, second derivative



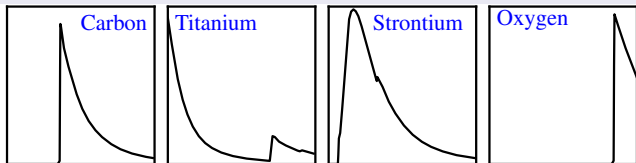
Original spectral components



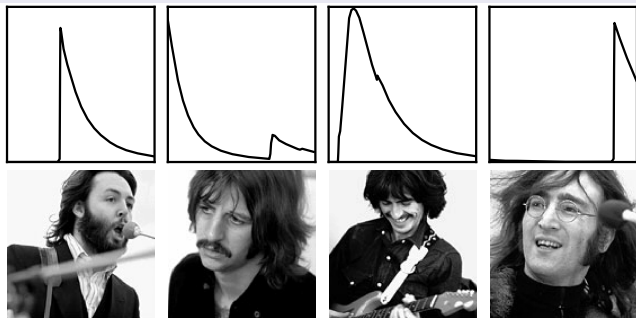
ICA result: High SNR, first derivative



Original spectral components



ICA result: High SNR, second derivative



Original spectral components



Low SNR: windows methods



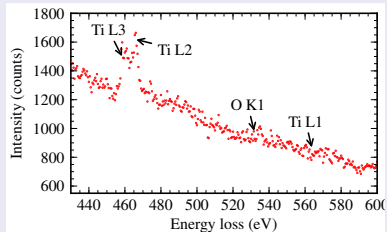
ICA result: Low SNR, first derivative



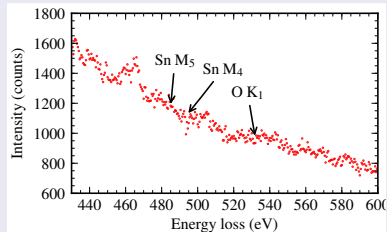
Spinodally decomposed $\text{SnO}_2/\text{TiO}_2$ multilayers

Noise reduction by dimensionality reduction

EEL spectrum Ti rich



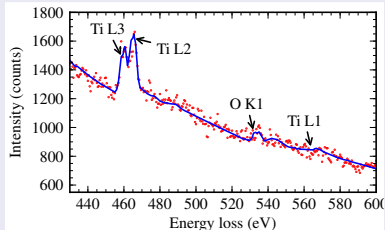
EEL spectrum Sn rich



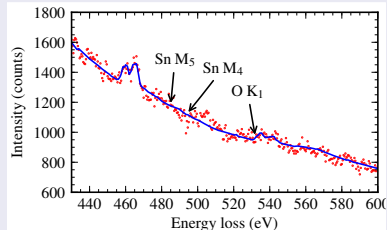
Spinodally decomposed $\text{SnO}_2/\text{TiO}_2$ multilayers

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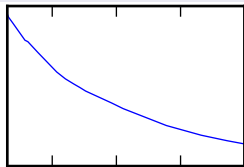
EEL spectrum Sn rich



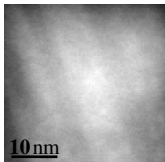
Spinodally decomposed $\text{SnO}_2/\text{TiO}_2$ multilayers

Independent component analysis

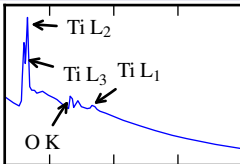
IC 1 Carbon



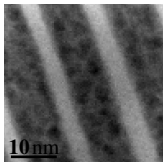
500 600 700
Energy loss (eV)



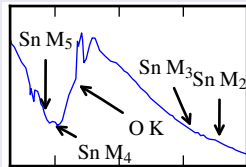
IC 2 Titanium oxide



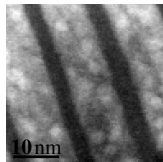
500 600 700
Energy loss (eV)



IC 3 Tin Oxide



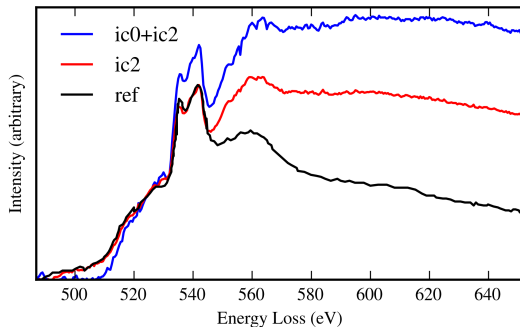
500 600 700
Energy loss (eV)



de la Peña et al., *Ultramicroscopy* 111 (2011)

Spinodally decomposed $\text{SnO}_2/\text{TiO}_2$ multilayers

The effect of plural scattering



- Singular value decomposition
 - is very useful for
 - Data denoising with no information loss
 - Rank estimation
 - Dimensionality reduction

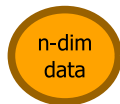
- Singular value decomposition
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 - The SNR improves with the number of trials in the dataset

- Singular value decomposition
 - is very useful for
 - Data denoising with no information loss
 - Rank estimation
 - Dimensionality reduction
 - The SNR improves with the number of trials in the dataset
- Independent component analysis
 - Separates sources from a mixture
 - The accuracy increases with SNR

- PCA: Jolliffe, Ian. Principal component analysis. John Wiley & Sons, Ltd, 2002.
- weighted PCA: Keenan, Michael R., and Paul G. Kotula. "Accounting for Poisson noise in the multivariate analysis of ToF-SIMS spectrum images." *Surface and Interface Analysis* 36.3 (2004): 203-212.
- ICA: Hyvärinen, A., Karhunen, J., and Oja, E. (2001). *Independent Component Analysis*. Wiley- Interscience

- PCA variants: robust PCA, online PCA
- Other BSS methods: non-negative matrix factorization (NMF), vertex component analysis (VCA)
- Tensor decomposition: Spiegelberg, Jakob, Ján Ruzs, and Kristiaan Pelckmans. "Tensor Decompositions for the Analysis of Atomic Resolution Electron Energy Loss Spectra." Ultramicroscopy (2017).

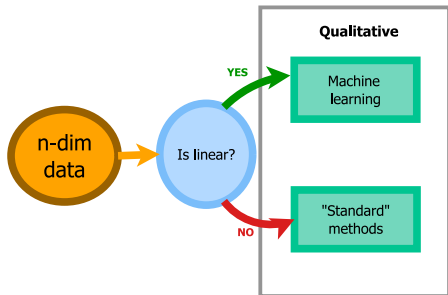
- 1 Introduction
 - Introduction
- 2 Model based quantification
 - The integration method
 - The curve fitting method
 - Multi-dimensional curve fitting
 - Practical application: Analytical tomography
- 3 Machine learning
 - Introduction
 - EELS core-loss analysis
- 4 Summary
 - Summary



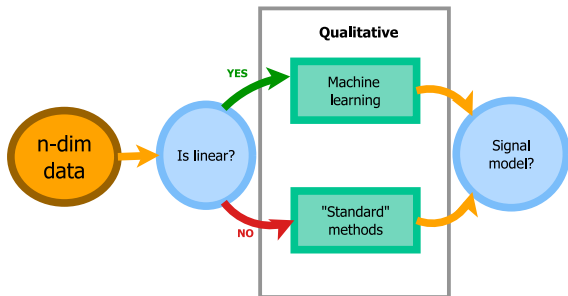
Multi-dimensional data analysis workflow



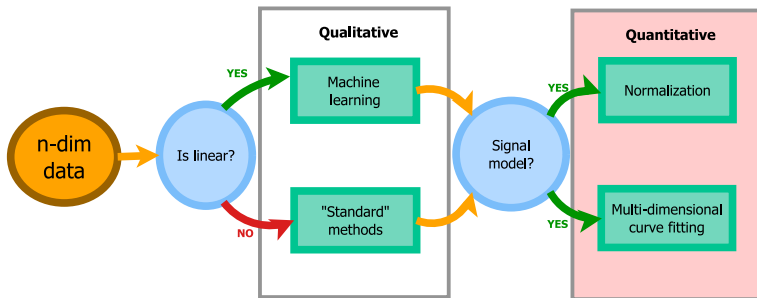
Multi-dimensional data analysis workflow



Multi-dimensional data analysis workflow



Multi-dimensional data analysis workflow



Thank you all for you attention



